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Advanced Resource Management in Automotive Networks

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Trend 1: New applications

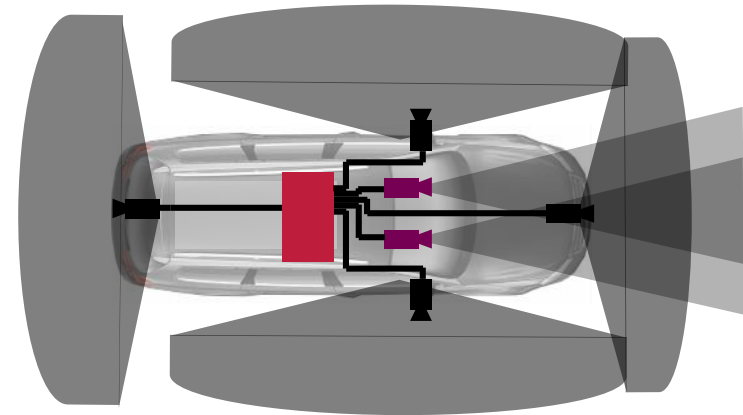
- networks with IP traffic via car-to-X communication
- communication with a cloud
- *primarily best effort*

Trend 2: Quickly growing sensor traffic

- high resolution sensors for autonomous driving (e.g. LIDAR, radars)
- which are redundant
- in consequence high bandwidth communication and limited network latency

Trend 3: Complex low latency traffic

- backbone function: legacy, future drives, highly interactive functions, ...
- low to medium volume, low latency traffic



- vehicle is a **mixed criticality** system
 - design and operation governed by functional safety standard ISO26262
 - classifies functions in criticalities ASIL D to ASIL A and non classified QM
 - all computing and communication involved in an ASIL A to D function must adhere to a **highly structured and constrained design process**
 - network focus shifts towards critical network traffic
 - traditional vehicles: little critical communication, most communication volume QM
 - including advanced driver assistance: control is driver responsibility
 - **future vehicles**: higher automation levels lead to **critical high-bandwidth traffic**
- **most future vehicle network traffic regulated by safety standard requirements**
- currently only manageable with **static network configuration**
 - safety concern!

Outline

- **Motivation**
- **Static Network Configuration**
- **Towards Network Dynamics**
 - **Fast and Safe Failover in the Network**
- **Exploiting Re-configuration**
 - **Car-2-X Communication**
- **Conclusions**

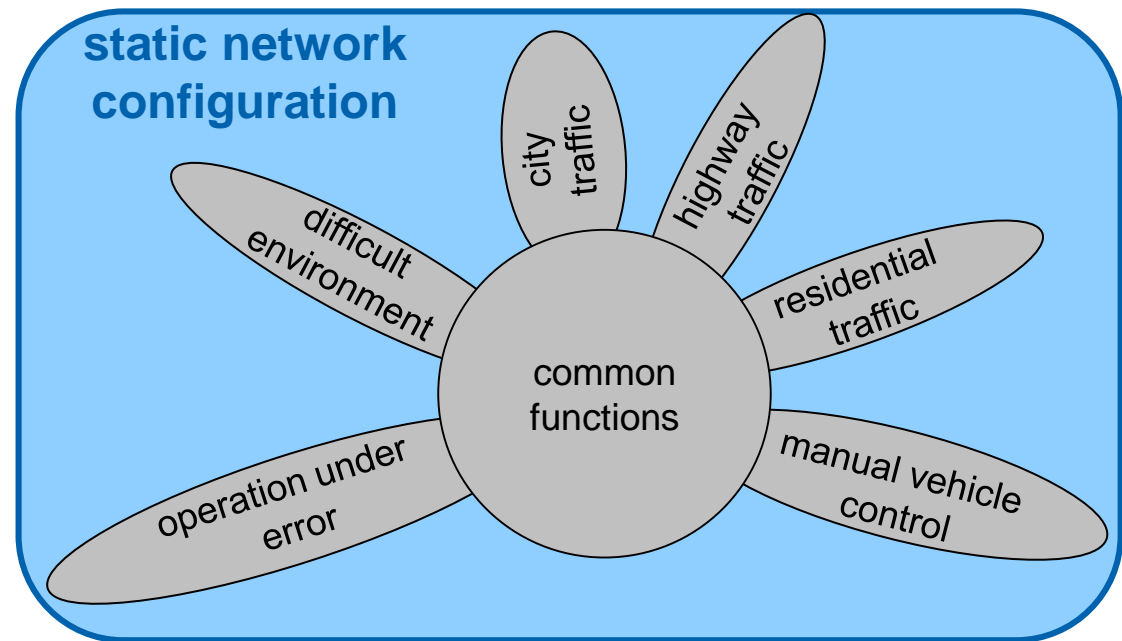
Work partially sponsored by Huawei



Static Configuration - Dilemma

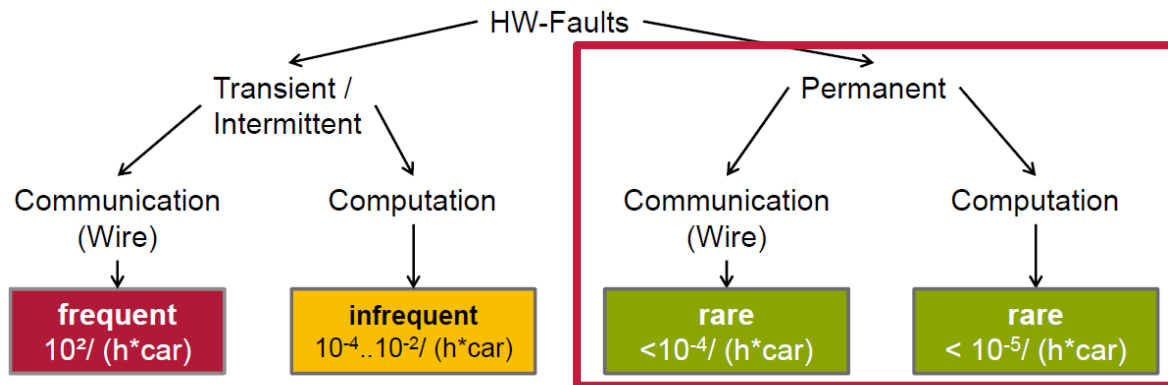
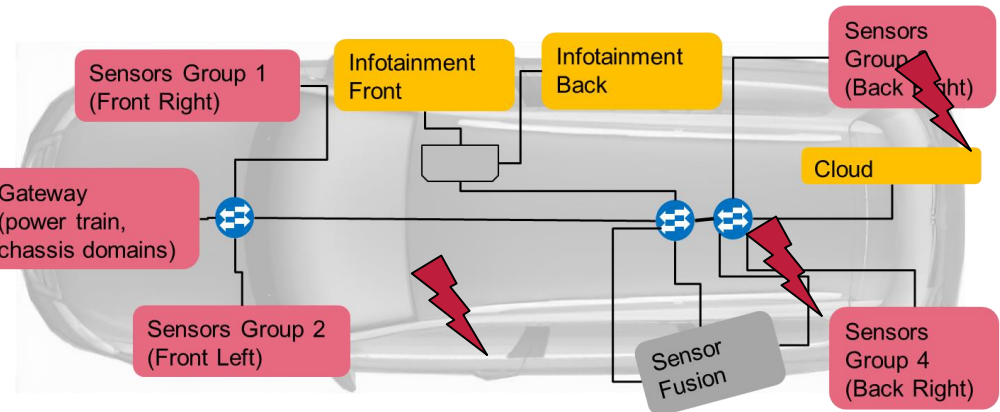
- **static configurations** must be designed for the **worst case**
 - of all driving and operating modes
 - of all traffic combinations under real-time constraints
 - of all transient and some static network errors
- leads to **redundancy** under almost all conditions
 - hardly exploitable under static TSN configuration

→ **expensive overprovisioning**



Example – Permanent faults!

- an automotive system must be able to handle permanent faults
 - fail-safe behaviour may not be enough for higher ASILs
 - fail-operational behaviour**
 - it may not be possible to bring the driver back into the control loop!
- fortunately one failure at a time
e.g. BroadR-Reach standard

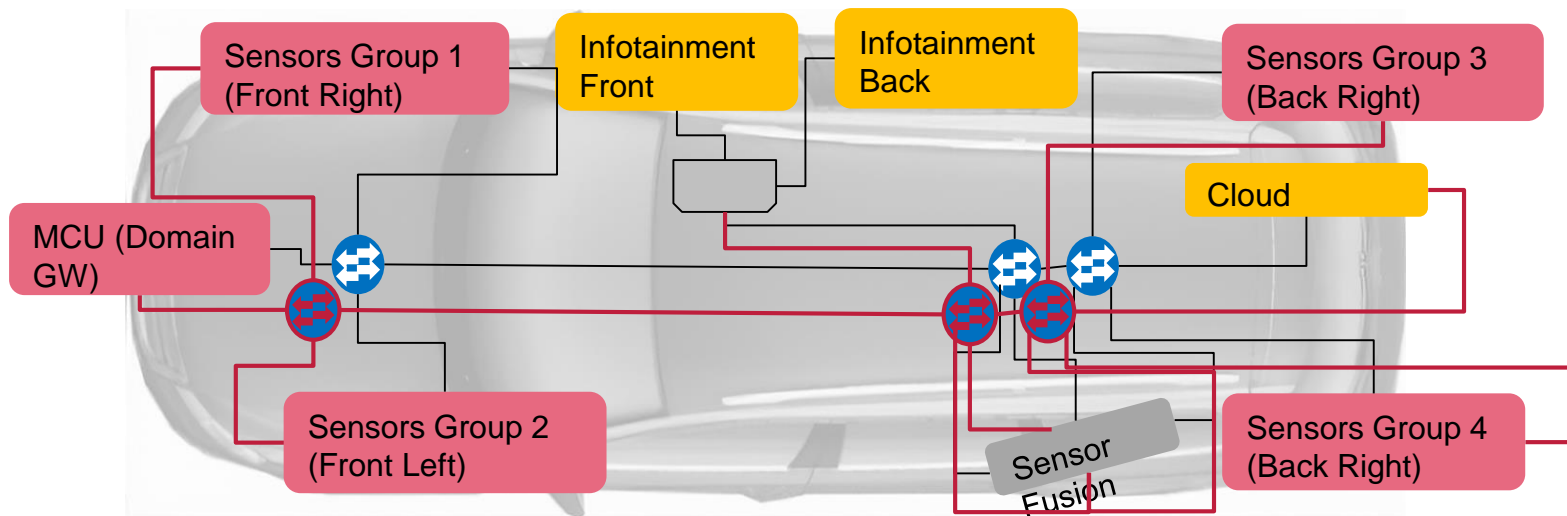
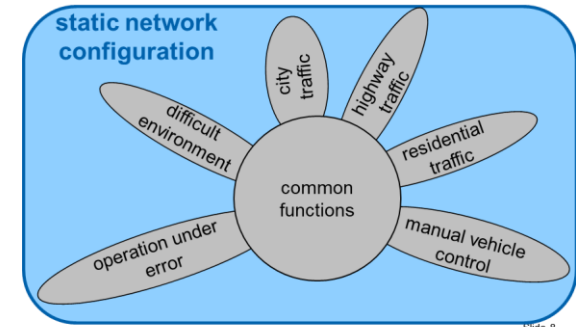


note: resulting computation errors strongly depend on state protection (memory)

Naïve approach – let's duplicate!

- introduce full hardware redundancy – duplicate whole network
 - example: 3 new switches, 12 new cables, 10 new ports
- immediate recovery at a high cost
 - overprovisioning in error-free case
 - including cost of maintenance, weight and power consumption

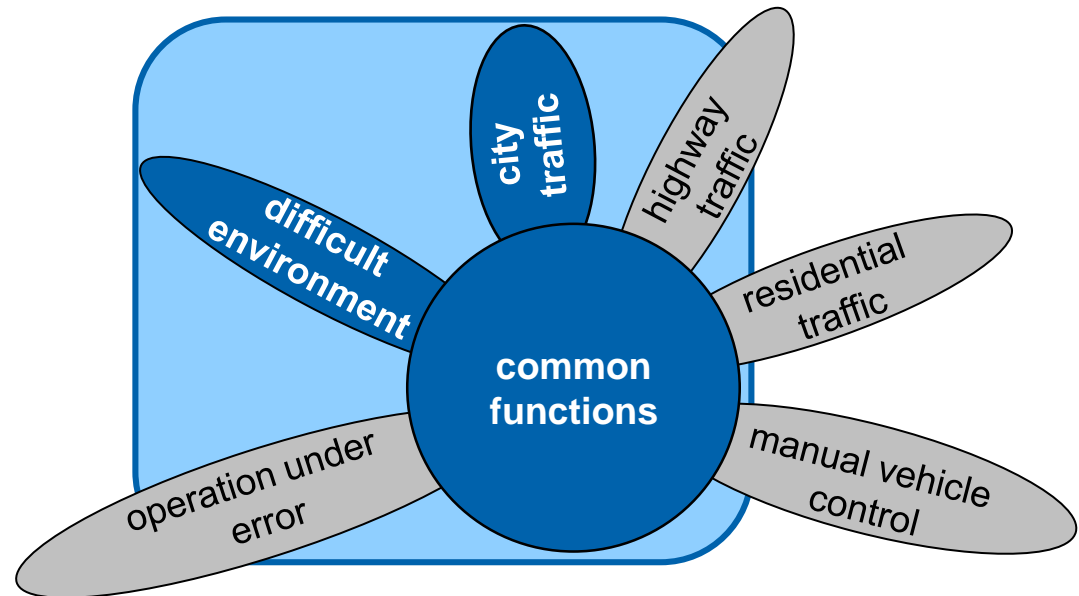
Overprovisioning



Towards Network Dynamics

- reduce redundancy by **adaption** to current communication requirements
 - great opportunity for **vehicle cost and performance optimization**
 - but must guarantee **real-time, safety, and network standard** compatibility
- adaptation requires **dynamic network re-configuration**
 - is dynamic re-configuration realistic?
- **And most of all is it safe?**

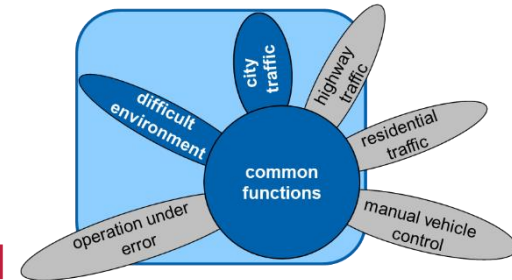
**network
adaptation**



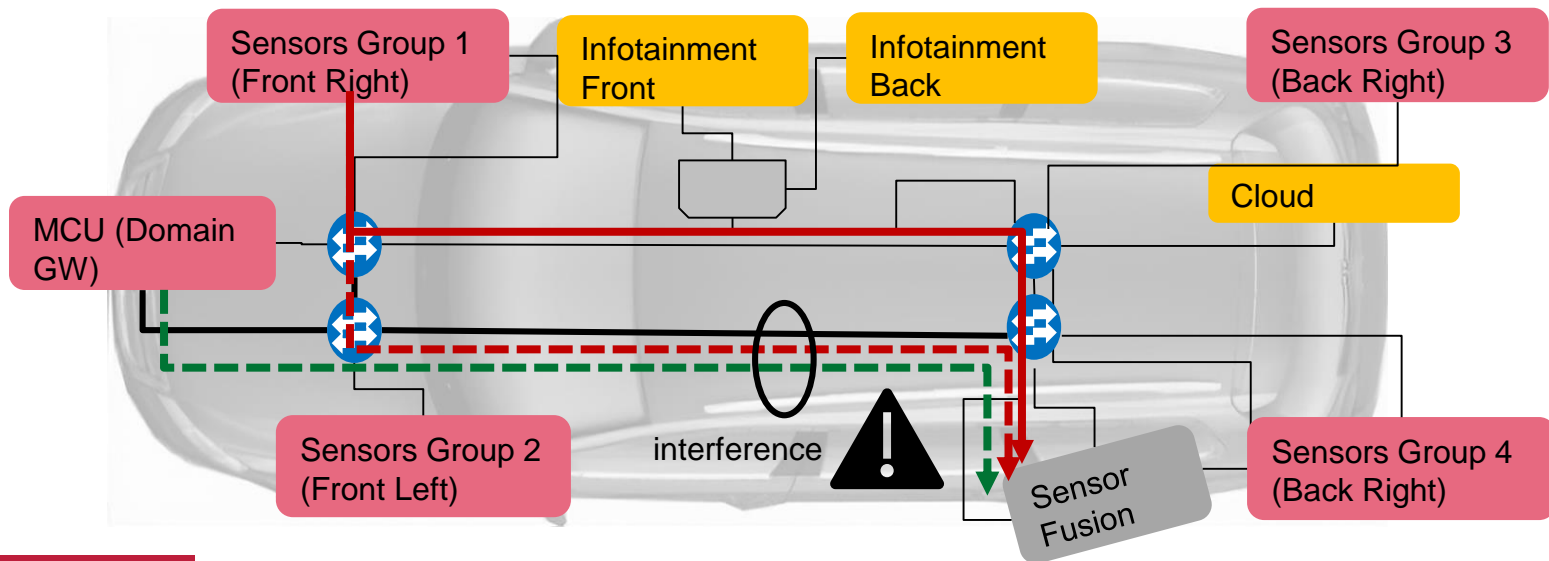
Alternative – Limited Redundancy

- redundant paths through the network such as ring- based topologies
 - example : 1 new switch, 3 links, 1 port
- redundant transmissions e.g. TSN FRER (IEEE 802.1CB)
 - zero extra delay but permanent overhead
- automated path detection and routing
 - may endanger safety or high permanent overhead

network
adaptation



**Uncoordinated
reallocation**



Managing Dynamic Re-configuration

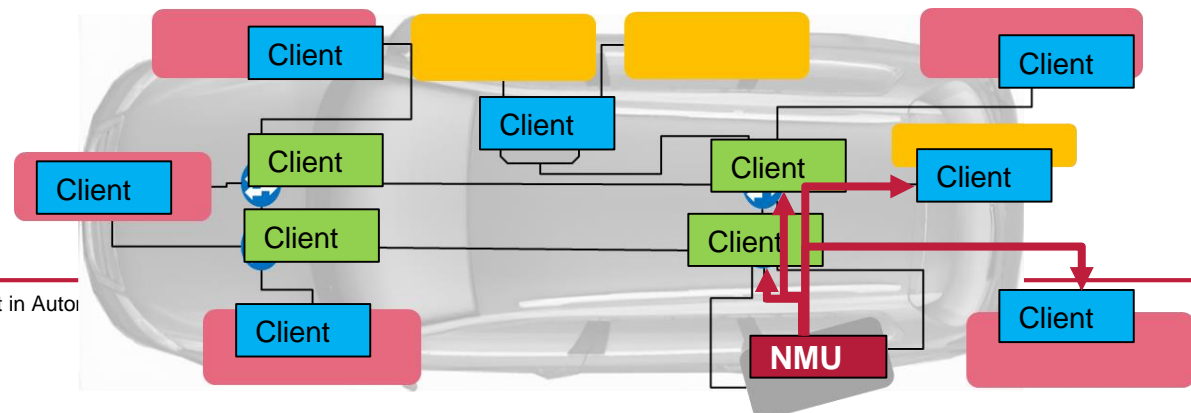
- our alternative solution uses **overlay network** for **controlled loss-free re-configuration in real-time**
 - **key challenge : preserving safety during mode-changes**

- **automotive TSN networks use many parameters for adaptation and optimization**
 - TSN standard offers interfaces to configure switches and network interfaces
 - may use IEEE 802.1Qcc protocols for network parameter distribution
 - but currently **no run-time configuration** due to **missing transition guarantees**

Overlay Network for Real-time Loss-free Re-configuration



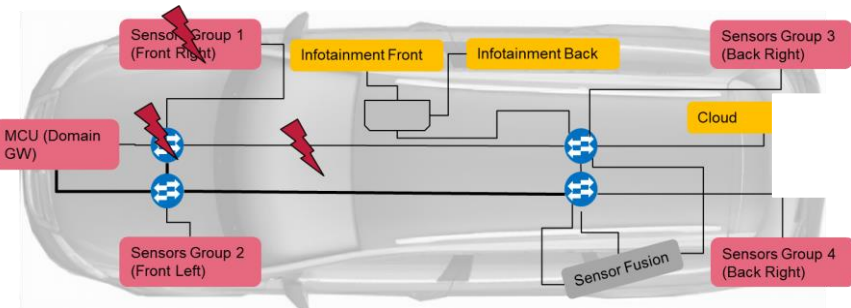
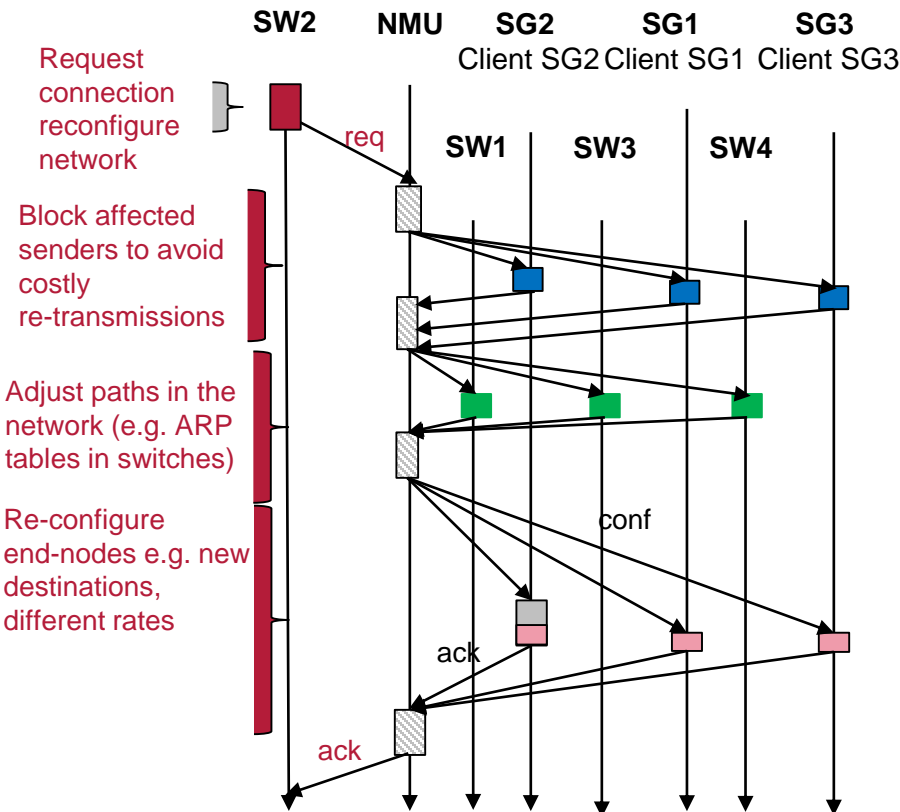
- Decouple flow and network management
 - data layer – low-level flow-control method in automotive network responsible for switching packets/frames
 - control layer – global and dynamic arbitration
 - clients in switches – like SDN
 - clients in end nodes – unlike SDN
- **Network Management Unit (NMU)**
 - central scheduling function with guaranteed timing – unlike SDN
- Protocol based synchronization
 - protocol for safe mode changes at runtime!
 - key enabling feature of the technology!



Overlay Protocol Requirements

- not that easy to make the re-configuration **safe**
 - protocol itself must be **resilient to transient errors**
 - order of re-configuration must **avoid QoS violation**
 - **re-configuration timing** must be **bounded**

Fast and Safe Mode-Change in the Network

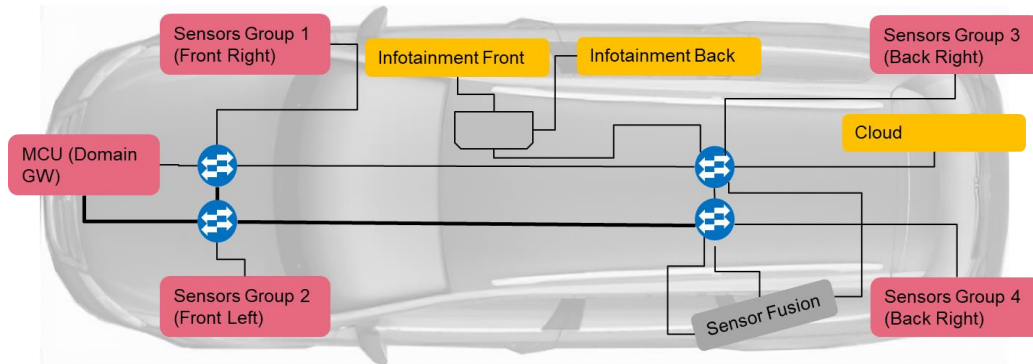


- block senders to avoid dropped packets
- load pre-configured router settings
- changed destination (IP)
- re-configure sensors (switch off radars, adjust cameras)
- And restart transmissions

Timing must allow
rollback
at any moment
to the safe state!

latency
<= 10 to 50 ms

Demo Setup



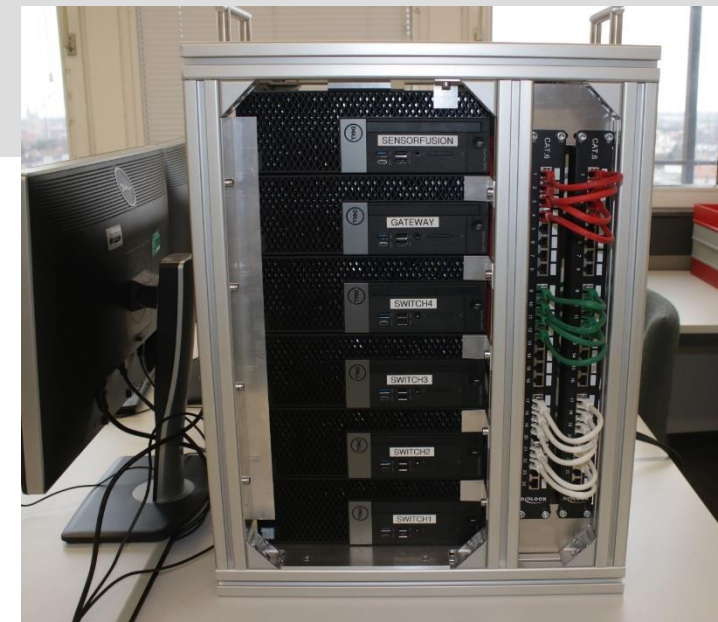
MCU (Domain GW)



Sensor Fusion



Sensors Groups



Intel Core i5-8400 CPU @ 2.8 GHz
x 6cores, 8192MB DDR4-2666 SDRAM
Intel I340-T4 Ethernet adapters 1Gbit

Allwinner H3 SoCs
(1GHz Quad-Core ARM Cortex-A7 @ 1.296GHz,
1GB DDR3-1333 SDRAM)
Allwinner Ethernet Adapter 1Gbit

Linux network stack (5.0.0-38-generic x86-64)

Clients + NMU C-libraries running in user-space

AVB Ethernet schedulers according to the IEEE 802.1Qav, IEEE 802.1QAS standards.

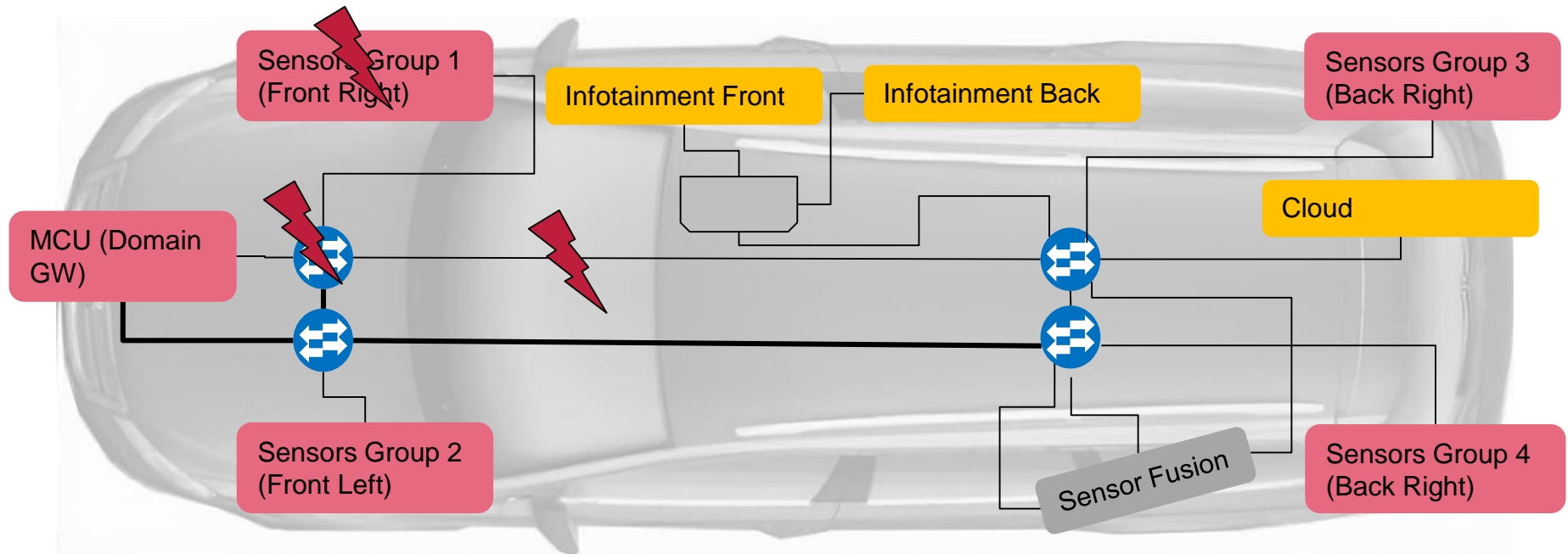


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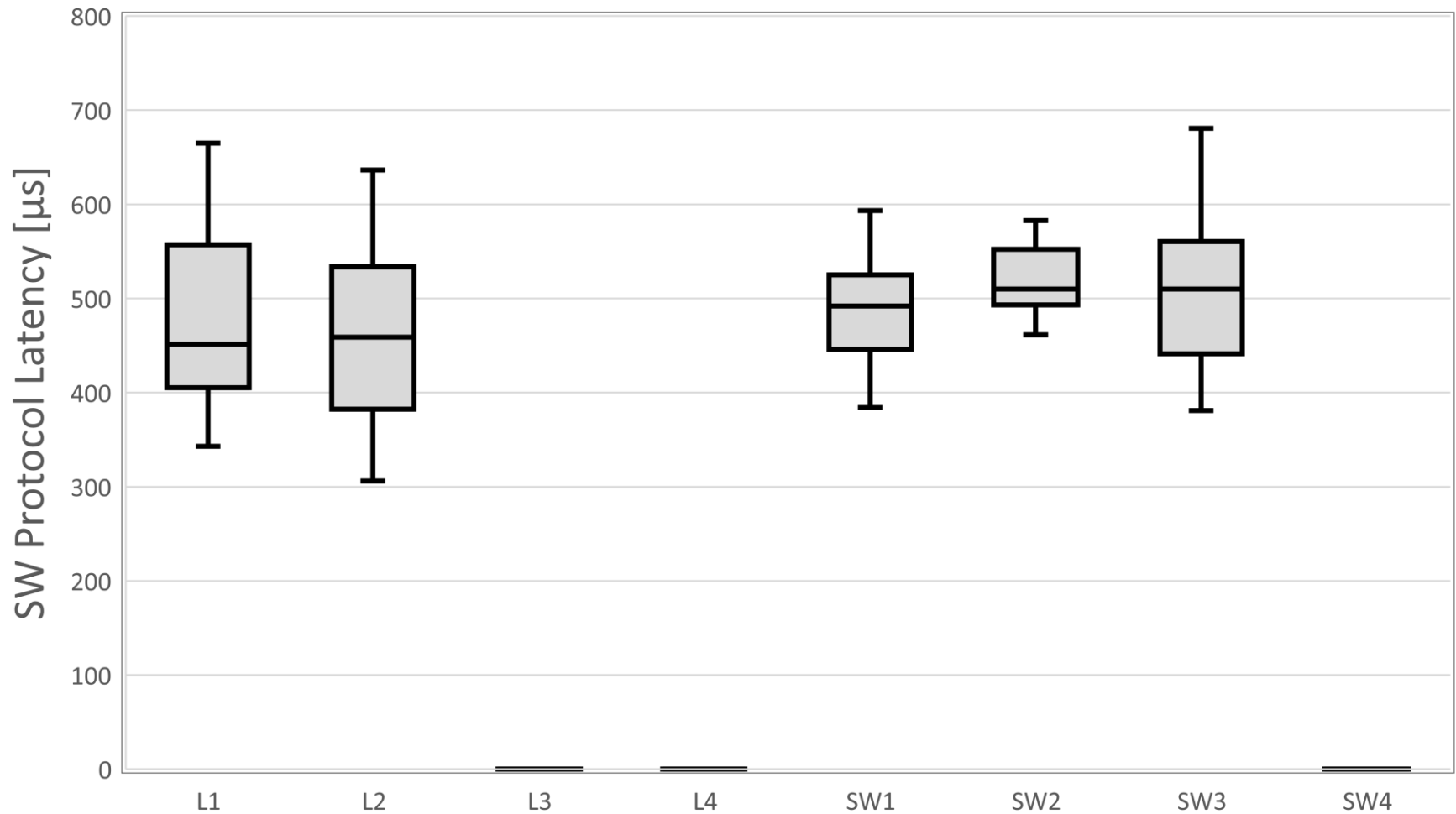
Advanced Resource Management in Automotive Networks | Adam Kostrzewa | IDA, Braunschweig | August 2020

Considered Scenarios

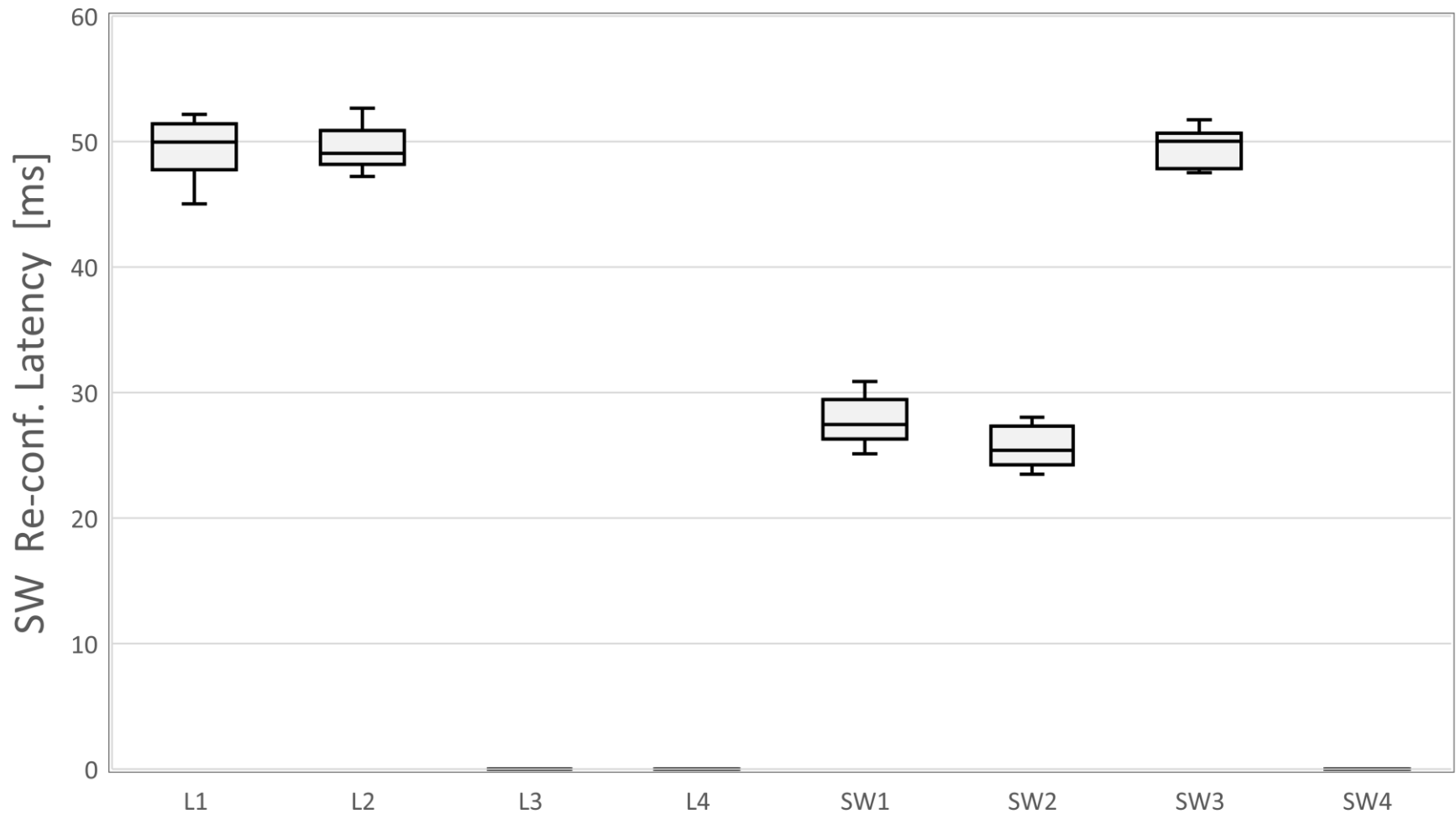
- Scenario 1 – SG unit is down
- Scenario 2 – Backbone link is down
- Scenario 3 – Switch is down



Demo Results – Protocol Overhead



Demo Results with NIC Re-conf. Latency



Comparison with Other Solutions

Protocol	Vendor	Topology	Failover time (max. 10 switches)
STP	IEEE Standard	Any	>30 s
RSTP (802.1w)	IEEE Standard	Any	Several Seconds
HiPER Ring	Hirshmann	Ring	200-500 ms
Turbo Ring	Hirshmann	Ring	<200ms
S-Ring	GarrettCom	Ring	<250 ms
RS-Ring	GarrettCom	Ring	<100 ms
RapidRing	Contemporary Controls	Ring	<300 ms
eRSTP	Siemens	Any	<50 ms (ring only)
RSTP (802.1D-2004)	IEEE Standard	Any	<50 ms (ring only)
Fast Protocol-based Reconfiguration		Any	<1 ms protocol overhead ~ 50ms linux-based

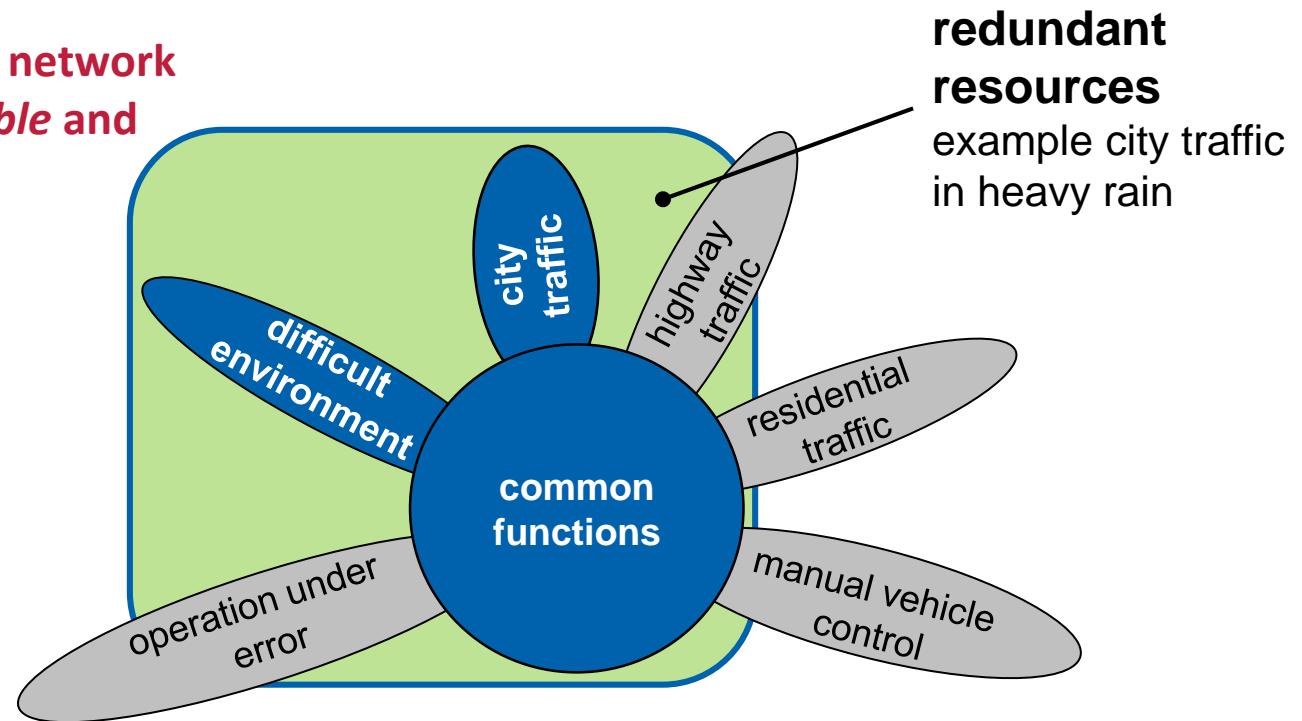
automotive network requirements: below 100 ms AVNu Alliance or even 50ms [2]

Comparison of ethernet-based network reconfiguration protocols based on [4] and [5].

Exploiting Re-configuration

- Dynamic re-configuration leaves **redundant resources** under almost all conditions
- Overlay network can make **redundancy available for predictable QM traffic**

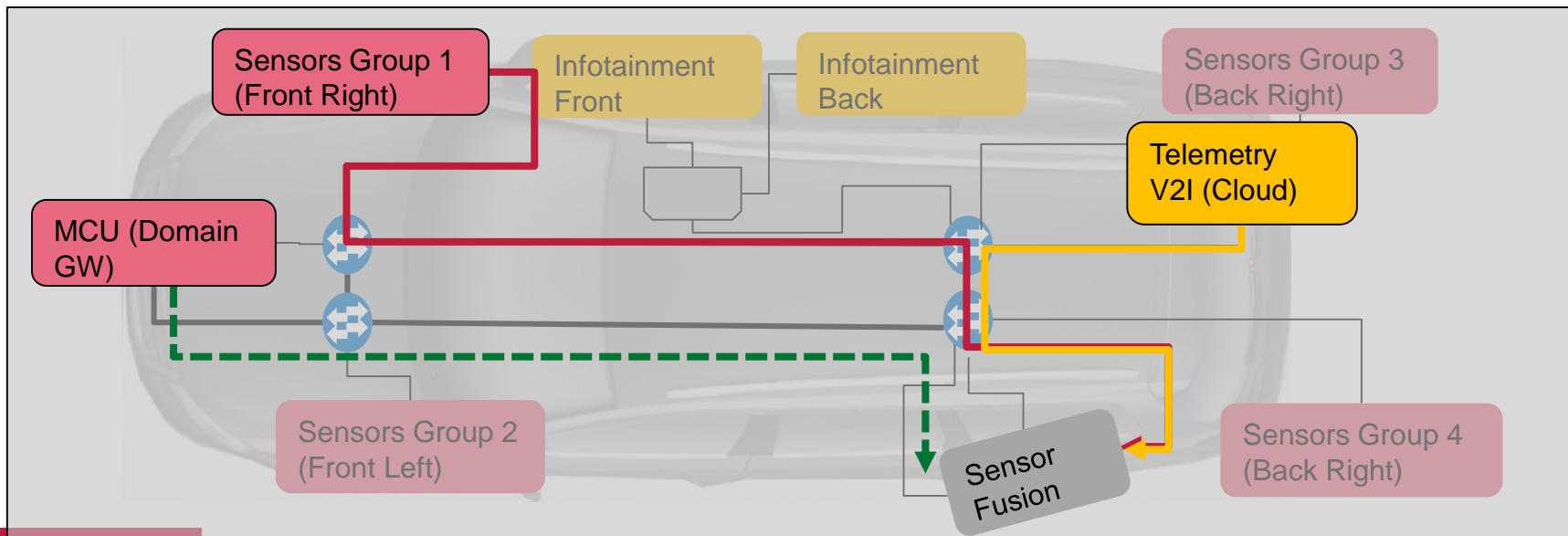
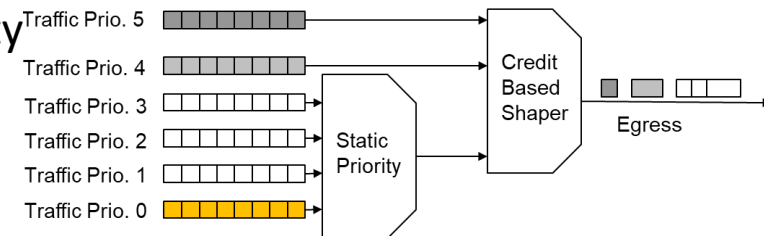
What if we could exploit network redundancy for *predictable* and *performant* dynamic communication?



Example Cloud Integration

- **Redundant resources only partially utilized**
 - example: permanent faults are rare, e.g. once per component lifetime
- How to provide access to the Sensor Fusion?
- Right now cloud traffic is best effort with low priority
 - long latencies / low bandwidth
 - and/or dropped packets

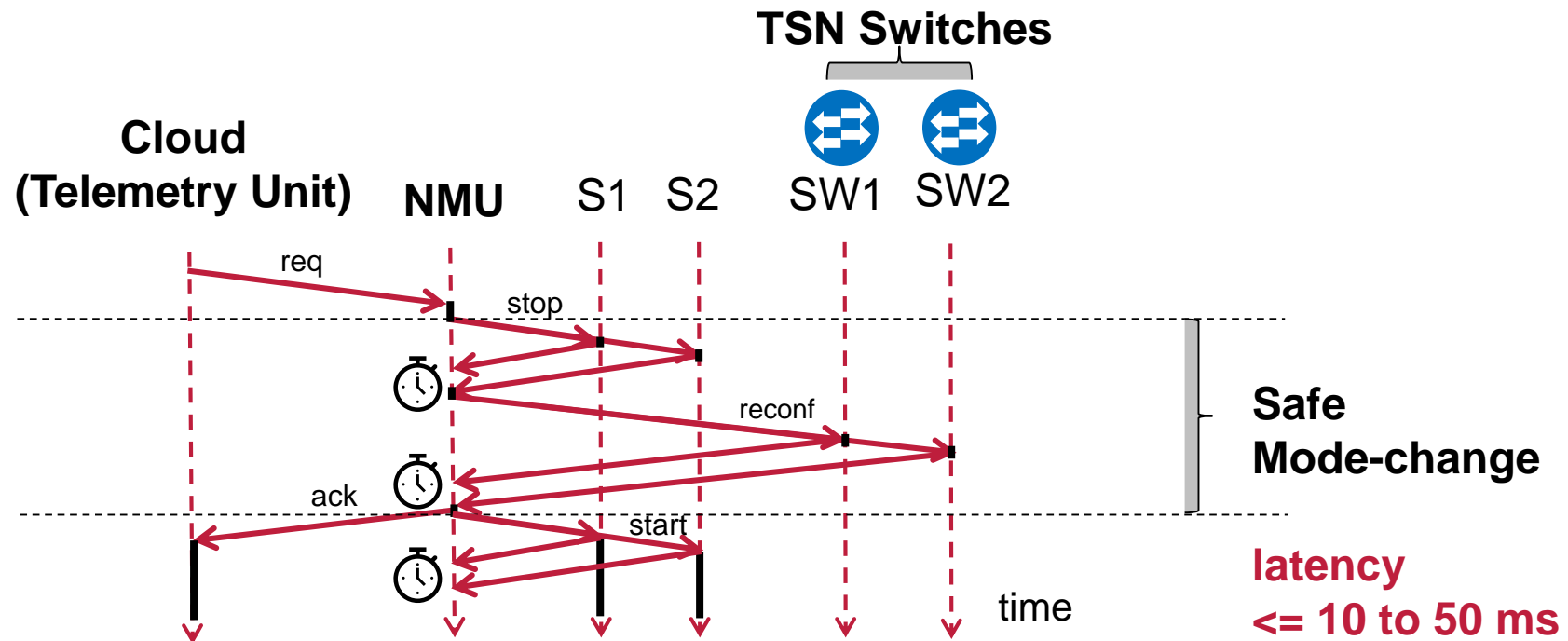
TSN Scheduler



-
- The diagram illustrates a vehicle network architecture with the following components and connections:
- MCU (Domain GW)**: The central control unit, shown in a pink box on the left.
 - Sensors Group 1 (Front Right)**: A pink box at the top left.
 - Sensors Group 2 (Front Left)**: A pink box at the bottom left.
 - Sensors Group 3 (Back Right)**: A pink box at the top right.
 - Sensors Group 4 (Back Right)**: A pink box at the bottom right.
 - Infotainment Front**: A yellow box at the top center.
 - Infotainment Back**: A yellow box at the top center-right.
 - Telemetry V2I (Cloud)**: A yellow box at the top right.
 - Sensor Fusion**: A grey box at the bottom center.
- Data Flow:**
- Red Solid Line:** Connects Sensors Group 1 to the MCU, then to the Infotainment Front, and finally to the Sensor Fusion unit.
 - Red Dashed Line:** Connects Sensors Group 2 to the MCU, then to the Infotainment Front, and finally to the Sensor Fusion unit.
 - Green Dashed Line:** Connects Sensors Group 2 to the MCU, then to the Infotainment Front, and finally to the Sensor Fusion unit.
 - Yellow Solid Line:** Connects Sensors Group 3 to the MCU, then to the Infotainment Back, and finally to the Sensor Fusion unit.
 - Yellow Solid Line (request):** Connects Sensors Group 4 to the MCU, then to the Infotainment Back, and finally to the Sensor Fusion unit.
 - Blue Bidirectional Arrows:** Indicate communication between the MCU and the Infotainment Front/Back units, and between the MCU and the Sensor Fusion unit.

Compatible, Safe, and Predictable Cloud Access

- partial dynamic re-configuration instead of complete network mode switch
- correct order and timing of actions!
- resilient rollback procedure e.g. ack msg + timeout



Example cloud access management

Benefits for Network Designer



- every vehicle has redundancy
 - cost can be minimized with dynamic re-configuration
- demo: huge benefits in cloud communication
 - efficient OTA communication almost for free!
 - the key enabling technology for efficient cloud communication
 - app1: collaborative perception with other vehicles and infrastructure;
 - 10x faster than SoA in demonstrator
 - app2: data collection for ML
- dynamic network management solves multiple problems with the same mechanism !

- *does dynamic re-configuration und safety constraints really work?*
 - yes, as proved by demonstrator
- *can we exploit re-configuration?*
 - **component cost saving** via **reduced network resources**
 - for wiring harness, switch, energy @ high real-time & safety guarantees
 - for switches, smaller buffers and/or more workload!
 - **multi-mode network functionality** at **low overhead**
 - **multi-mode systems with lower integration cost and higher performance**
 - example fail operational network re-configuration
 - **new system functions** and **improved user experience** by dynamic OTA network operation
 - **via exploitation of unused redundant resources and improved QM traffic management**
 - app1: **collaborative perception** with other vehicles and infrastructure;
 - app2: **data collection** for ML